Capacity of Right-Turn Lane at Signalized Intersection under Pedestrian-Bicycle Effect

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Abstract: The effect of pedestrian and bicycle infrastructure is used to analyze the capacity for right-turn lane at signalized intersection. Each cycle at the signalized intersection was divided into several periods. The effect of pedestrian and bicycle at each period was analyzed. The number of right-turn cars going through signalized intersection was calculated by using probability theory and mathematical statistics. The capacity under the effect of pedestrian and bicycle for right-turn lane at signalized intersection was deduced. The calculated results were deduced by using the survey data of two signalized intersections at Jinan city. The mean difference values are 8% and 10.1%, compared with VISSIM simulation results. The comparisons show that this model can fully describe the effect of pedestrian and bicycle to signalized intersection.

Keywords: Traffic engineering, Capacity, Pedestrian-bicycle, Signalized intersection, Right-turn lane.

1. Introduction

When there are heavy pedestrian and bicycle flows at a signalized intersection, the conflicts between pedestrian-bicycle flow and vehicle flow at right-turn lane are obvious. The vehicle flow is usually blocked by the pedestrian-bicycle flow crosswise, and the effect for the capacity of vehicle flow at right-turn lane is significant. A lot of factors are posed in HCM2010 [1] to describe the influence for the capacity of right-turn lane, such as signal timing, traffic composition, lane width, etc. Code for the design of urban road engineering method [2] and stop line method [3] make systematical description of the calculation method at a signalized intersection, and simply describe the impact of the pedestrian-bicycle flow to the vehicle flow at right-turn lane. Many studies [2, 4-8] focus on this impact, and many methods are used to deduce the capacity models, such as data fitting method.
[5, 8], gap acceptance theory [6, 7, 9], traffic flow wave theory [10] and mathematical statistics method [11]. In order to deduce capacity models, the concepts of bicycle group [6] and pedestrian group [7] were proposed separately to describe the distribution pedestrian and bicycle flows. Study [8] divides the vehicel-bicycle conflict at intersections into several units by using temporal separation and spatial separation method.

This paper focuses on the impacts of pedestrian-bicycle flow for right-turn lane at normal signalized intersection. Signal cycle is divided into several periods, and capacity model is developed. The calculated values of model are verified by VISSIM simulation results.

2. Conflicts between pedestrian-bicycle flow and vehicle flow

In the space domain, the transverse interference of right-turn vehicle flow is from the pedestrian-bicycle flow at an intersection entrance and an exit. When it is at a green phase, the agglomerated pedestrian and bicycle flows at pedestrian-bicycle stop line will continuously cross right-turn lane, and the vehicle flow will be blocked until all the agglomerated pedestrian and bicycle flows getting through. Fig. 1 is the schematic diagram of a normal intersection. The right-turn vehicle flow from southern entrance should pass through the pedestrian-bicycle flow of westward, eastward, northward and southward.

![Fig. 1. Diagram of right-turn vehicle flow passing through bicycle-pedestrian flow](image)

In the time domain, setting of bicycle-pedestrian phase usually accords to the vehicle phase. Therefore, east-westward and north-southward bicycle-pedestrian flows will cross through the intersection at different phases.

Taking east-westward phase for example, bicycle and pedestrian flows which cross the intersection can be illustrated as schematic diagram of Fig. 2. The agglomerated bicycle-pedestrian flow waits at western stop line until the signal indication changing to green, then go cross the stop line continuously. Hypothesize this time-period lasts HI. These flows spread to bicycle flow and pedestrian flow when the flows arrive to the right-turn lane at southern entrance. Hypothesize the time-period of bicycle flow going through right-turn lane lasts CD, and pedestrian flow lasts EF. The bicycle flow and pedestrian flow of these time-periods will have
a block effect for right-turn vehicle flow. Hypothesize the westward bicycle-pedestrian flow going through right-turn lane lasts time-period AB. And it will have a block effect for right-turn vehicle flow too. BC, DE and FG are the time-periods of stochastic bicycle-pedestrian flow going through right-turn lane.

Because the conflict mechanisms of the flows at entrance and exit are almost the same, Fig. 2 can describe the conflict mechanism of flows at exit too.

![Diagram](image)

Fig. 2. Spreading of bicycle-pedestrian flow

3. Modelling

There are five hypothesizes of this paper: (1) there is one right-turn lane at each typical intersection, (2) all the drivers and pedestrians obey the traffic law, (3) the intersection is once-cross street intersection, (4) the green times of bicycle and pedestrian are simplified as equal to the green time of vehicle, (5) other influencing factors are not considered.

3.1. Capacity model

The signal cycle time can be divided into three periods. And the capacity model of right-lane can be hypothesized as the following formula (1).

\[ C = \frac{3600}{T} \left( N_{EW} + N_{SN} + N_{R} \right) \]

where \( T \) is signal cycle time, \( N_{EW} \) is the number of vehicles going through at the east-westward green time of one signal cycle, \( N_{SN} \) is the number of vehicles going through at the north-southward green time of one signal cycle, \( N_{R} \) is the number of
vehicles going through at the red time of one signal cycle. And, \( N_R \) can be calculated by formula (2).

(2) \[
N_R = \frac{T - T_{SN} - T_{EW} - T_L}{H_r},
\]

where \( T_{SN} \) is the north-southward green time, \( T_{EW} \) is the east-westward green time, \( H_r \) is the headway of vehicle flow at right-lane, \( T_L \) is lost time.

3.2. \( N_{SN} \) and \( N_{EW} \) models

The number of vehicles going through at north-southward green time is the sum of vehicle going through at AB, BC, CD, DE, EF and FG periods. Parameter \( N_{SN} \) can be calculated as

(3) \[
N_{SN} = N_{bSN} + N_{pSN} + N_{SN1} + N_{SN2} + N_{SN3},
\]

where \( N_{bSN} \) is the number of vehicles going through a stochastic flow of bicycle-pedestrian at CD period, \( N_{pSN} \) is the number of vehicles going through a stochastic flow of bicycle-pedestrian at EF period, \( N_{SN1} \) is the number of vehicles going through the gap between bicycle flow and pedestrian flow at BC period, \( N_{SN2} \) is the number of vehicles going through at surplus time after agglomerated pedestrian flow.

In the same way, \( N_{SN} \) can be deduced using the abovementioned method. The following is the deduction of variables in (3).

3.3. Number of vehicles going through under conflicts with multi-bicycle and pedestrian flows

Let’s assume that the arrival distributions of bicycle flows and pedestrian flows obey the Poisson distribution \([8]\). And the bicycles or pedestrians can overtake freely. Hypothesizing the arrival rate is \( \lambda \), the distribution function is \( F(t) = 1 - \exp(-\lambda t) \). The probability of headway more than \( t \) (minutes) is \( f(t) = P(ht > t) = \exp(-\lambda t) \). Hypothesizing there are two independent flows, their arrival rate are \( \lambda_1 \) and \( \lambda_2 \). The following formula can be deduced from conditional probability:

\[
f_{12}(t) = f_1(t) \cdot f_2(t) = \exp(-\lambda_1 t) \cdot \exp(-\lambda_2 t) = \exp[-(\lambda_1 + \lambda_2) t].
\]

Therefore, when two flows mixed to one flow, the mixed flow still obeys Poisson distribution with the arrival rate of \( \lambda_1 + \lambda_2 \).

Let’s assume that a certain bicycle-pedestrian flow obeys Poisson distribution. The duration time is \( T \). The headway of right-turn vehicle flow is \( H_r \). The critical gap vehicle flow going through bicycle-pedestrian flow is \( t_0 \). Subsection
summation method is used to derive the number of right-turn vehicles going through at time segment $T$.

If $0 < t < t_0$, there is 0 vehicle going through. The probability is $F(0) = 1 - \exp(-\lambda t_0)$. The frequency is $N_0 = \lambda T \cdot F(0) = \lambda T \cdot [1 - \exp(-\lambda t_0)]$.

If $t_0 + (i - 1) \cdot \overline{H}_i < t < t_0 + i \cdot \overline{H}_i$, there is $i$ vehicles going through. The probability is $F(i) = \exp\{-\lambda [t_0 + (i - 1) \overline{H}_i]\} - \exp\{-\lambda [t_0 + i \cdot \overline{H}_i]\}$. The frequency is

$$N_i = \lambda T \cdot F(i) = \lambda T \cdot \exp\{-\lambda [t_0 + (i - 1) \overline{H}_i]\} - \lambda T \cdot \exp\{-\lambda [t_0 + i \cdot \overline{H}_i]\},$$

where $i = 1, 2, \ldots, n$.

The number of right-turn vehicles going through at time segment $T$ is deduced to formula

$$N = \sum_{i=0}^{n} (N_i \cdot i) = \sum_{i=0}^{n} (\lambda T \cdot F(i) \cdot i) =$$

$$= \lambda T \cdot \left\{ \sum_{i=0}^{n} \exp\{-\lambda [t_0 + (i - 1) \overline{H}_i]\} \cdot n \cdot \exp(-\lambda t_0 + n \cdot \overline{H}_i) \right\}.$$

That formula, by using the method of sum of the geometric progression can be deduced to

$$N = \lambda T \cdot \left\{ \frac{\exp(-\lambda t_0) - \exp(-\lambda n \cdot \overline{H}_i)}{1 - \exp(-\lambda \overline{H}_i)} \right\} - n \cdot \exp(-\lambda t_0 + n \cdot \overline{H}_i).$$

Let be $n \to \infty$, formula (5) can be deduced to

$$N = \frac{\lambda T \cdot \exp(-\lambda t_0)}{1 - \exp(-\lambda \overline{H}_i)}.$$

Let’s assume that the volumes of bicycle flow and pedestrian flow westward and eastward are $Q_{WE}$, $Q_{pWE}$, $Q_{WE}$, and $Q_{pEW}$, corresponding to the arrival rates as $\lambda_{pWE}$, $\lambda_{pEW}$, $\lambda_{WE}$ and $\lambda_{pEW}$. When the agglomerated bicycle flow and pedestrian flow arrive eastward to right-turn lane of southern entrance, the arrival rates are $\tilde{\lambda}_{WE}$ and $\tilde{\lambda}_{pWE}$. The relationship between $\lambda$ and $Q$ is $\lambda = Q / 3600$.

Parameters $N_{BEW}$, $N_{BEW1}$, $N_{BEW2}$ and $N_{BEW3}$ can be calculated by

$$N_{BEW} = \frac{(\tilde{\lambda}_{pWE} + \tilde{\lambda}_{pEW} + \tilde{\lambda}_{pEW}) \cdot T_{CD} \cdot \exp\{-(\tilde{\lambda}_{pWE} + \tilde{\lambda}_{pEW} + \tilde{\lambda}_{pEW}) t_0\}}{1 - \exp\{-(\tilde{\lambda}_{pWE} + \tilde{\lambda}_{pEW} + \tilde{\lambda}_{pEW}) \overline{H}_i\}},$$

$$N_{pEW} = \frac{(\tilde{\lambda}_{pWE} + \tilde{\lambda}_{pEW} + \tilde{\lambda}_{pEW}) \cdot T_{EF} \cdot \exp\{-(\tilde{\lambda}_{pWE} + \tilde{\lambda}_{pEW} + \tilde{\lambda}_{pEW}) t_0\}}{1 - \exp\{-(\tilde{\lambda}_{pWE} + \tilde{\lambda}_{pEW} + \tilde{\lambda}_{pEW}) \overline{H}_i\}},$$

$$N_{EW1} = \frac{(\tilde{\lambda}_{pEW} + \tilde{\lambda}_{pEW}) \cdot T_{BC} \cdot \exp\{-(\tilde{\lambda}_{pEW} + \tilde{\lambda}_{pEW}) t_0\}}{1 - \exp\{-(\tilde{\lambda}_{pEW} + \tilde{\lambda}_{pEW}) \overline{H}_i\}},$$

$$N_{EW2} = \frac{(\tilde{\lambda}_{pWE} + \tilde{\lambda}_{pEW} + \tilde{\lambda}_{pEW}) \cdot T_{EF} \cdot \exp\{-(\tilde{\lambda}_{pWE} + \tilde{\lambda}_{pEW} + \tilde{\lambda}_{pEW}) t_0\}}{1 - \exp\{-(\tilde{\lambda}_{pWE} + \tilde{\lambda}_{pEW} + \tilde{\lambda}_{pEW}) \overline{H}_i\}},$$

$$N_{EW3} = \frac{(\tilde{\lambda}_{pWE} + \tilde{\lambda}_{pEW} + \tilde{\lambda}_{pEW}) \cdot T_{CD} \cdot \exp\{-(\tilde{\lambda}_{pWE} + \tilde{\lambda}_{pEW} + \tilde{\lambda}_{pEW}) t_0\}}{1 - \exp\{-(\tilde{\lambda}_{pWE} + \tilde{\lambda}_{pEW} + \tilde{\lambda}_{pEW}) \overline{H}_i\}}.$$
(10) \[ N_{EW2} = \frac{(\lambda_{0WE} + \lambda_{pWE} + \lambda_{sEW} + \lambda_{pEW}) \cdot T_{DE} \cdot \text{Exp}\{-(\lambda_{0WE} + \lambda_{pWE} + \lambda_{sEW} + \lambda_{pEW})t_H}\}}{1 - \text{Exp}\{-(\lambda_{0WE} + \lambda_{pWE} + \lambda_{sEW} + \lambda_{pEW})t_H}\}}. \]

(11) \[ N_{EW3} = \frac{(\lambda_{0WE} + \lambda_{pWE} + \lambda_{sEW} + \lambda_{pEW}) \cdot T_{FG} \cdot \text{Exp}\{-(\lambda_{0WE} + \lambda_{pWE} + \lambda_{sEW} + \lambda_{pEW})t_H}\}}{1 - \text{Exp}\{-(\lambda_{0WE} + \lambda_{pWE} + \lambda_{sEW} + \lambda_{pEW})t_H}\}}. \]

where \( T_{AB} \), \( T_{BC} \), \( T_{CD} \), \( T_{DE} \), \( T_{EF} \) and \( T_{FG} \) are the duration times of time segments AB, BC, CD, DE, EF and FG.

3.4. Arrival rates of agglomerated flow and time segments

Let’s assume that the speeds at the front of agglomerated bicycle flow and pedestrian flow are \( V_{b1} \) and \( V_{p1} \). The speeds at the end of agglomerated bicycle flow and pedestrian flow are \( V_{b2} \) and \( V_{p2} \). The length of bicycle lane and crosswalk is \( L \), the widths are \( W_b \) and \( W_p \). The numbers of agglomerated bicycles and pedestrians waiting at eastern stop line at the end of red signal are \( N_{bE} \) and \( N_{pE} \). The numbers of agglomerated bicycles and pedestrians waiting at western stop line at the end of red signal are \( N_{bW} \) and \( N_{pW} \).

Parameters \( N_{bE} \), \( N_{pE} \), \( N_{bW} \) and \( N_{pW} \) can be calculated by:

(12) \[ N_{bE} = Q_{bWE}(T - T_{EW})/T, \]
(13) \[ N_{pE} = Q_{pWE}(T - T_{EW})/T, \]
(14) \[ N_{bW} = Q_{bWE}(T - T_{WE})/T, \]
(15) \[ N_{pW} = Q_{pWE}(T - T_{WE})/T. \]

Let’s assume that the duration times of the agglomerated bicycles and pedestrians going westward and eastward are \( T_{bHI} \), \( T_{pHI} \), \( T_{bAB} \) and \( T_{pAB} \). Hypothesize the duration time is proportional to volume and inversely proportional to lane width.

Parameters \( T_{bHI} \), \( T_{pHI} \), \( T_{bAB} \) and \( T_{pAB} \) can be calculated by:

(16) \[ T_{bHI} = a_{b1} \cdot Q_{bWE}(T - T_{WE})/(TW_b), \]
(17) \[ T_{pHI} = a_{p1} \cdot Q_{pWE}(T - T_{WE})/(TW_p), \]
(18) \[ T_{bAB} = a_{b1} \cdot Q_{bAB}(T - T_{EW})/(TW_b), \]
(19) \[ T_{pAB} = a_{p1} \cdot Q_{pAB}(T - T_{EW})/(TW_p). \]

The coordinate values of points C, D, E and F can be calculated by:

(20) \[ T_C = L/V_{b1}, \]
The arrival rates of eastward agglomerated flow arriving at right-turn lane can be calculated by:

\[ \lambda_{b\text{WE}} = \lambda_{b\text{HW}} \cdot \frac{T_{b\text{HW}}}{T_{b\text{CD}}}, \]

\[ \lambda_{p\text{WE}} = \lambda_{p\text{HW}} \cdot \frac{T_{p\text{HW}}}{T_{p\text{EF}}}. \]

3.5. Special cases

(1) If the crosswalk is very short, the condition of \( T_{b} > T_{c} \) may appear. The time series in turn are AC, CB, BD, DE, EF and FG. The agglomerated flow will block the right-turn vehicles at time segments AC and CB. The calculation method after time point B obeys Section 3.4.

(2) If the crosswalk is very short, or the bicycle-pedestrian flow is heavy, the condition of \( T_{c} > T_{b} \) may appear. The time series in turn are AB, BC, CE, ED, DF and FG. The arrival rate of bicycle-pedestrian flow at time segment ED is \( \lambda_{b\text{WE}} + \lambda_{p\text{WE}} + \lambda_{o\text{WE}} + \lambda_{p\text{EW}} \). The segment times of CE, ED and DF should be recalculated.

(3) If \( T_{f} > T_{E\text{W}} \), the green signal can’t meet the demand of pedestrian flow to go through crosswalk. Twice-cross street should be considered for signal timing.

4. Example and simulation verification

Basic data is collected by field survey at Jingshi Road& Nanxinzhuanxi Road intersection Jiluo Road& Beiyuan Road intersection of Jinan city, China. And the capacity values are calculated by using the basic data. Capacity value is hard to acquire by field survey, so VISSIM simulation is used to verify the calculating results. The simulation diagram is shown in Fig. 3.
To compare calculated values with simulated values is used the next formula:

\[ R_D = \frac{\sum_{i=1}^{10} |S_i - C_i|}{\sum_{i=1}^{10} C_i}, \]

where \( R_D \) is the mean deviation ratio, \( S_i \) is simulated value, \( i \) is the sample number, \( C_i \) is calculated value. The comparison diagrams are shown at Fig. 4 and Fig. 5.
The $R_D$ value of Jingshi Road & Nanxinzhuanxi Road intersection is 8%, and the $R_D$ value of Jiluo Road & Beiyuan Road intersection is 10.1%. The calculated value fits simulated value very well. Therefore, the method is suitable to calculate the capacity of right-turn lane.

4. Conclusion

(1) This study focus on the conflicts between pedestrian-bicycle flow and vehicle flow at right-turn lane, and puts forward the capacity model right-turn lane. It provides the theoretical basis for the studies of capacity under heavy pedestrian-bicycle flow.

(2) If the length of crosswalk is very long or the volume of pedestrian flow is heavy, it is hard for once-cross street. Twice-cross street should be considered for signal timing.

(3) There are many influencing factors for the driving of right-turn vehicle. One right-turn lane at typical intersection is considered in the paper. The scholars can focus on the modifications of lane width, traffic composition, and multiple right lanes.

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References


